



2.2 Trouble Shooting

Error Indication	Error Cause	Possible Error Source	Corrective Procedure
	no mains voltage supply	mains fuse or circuit breaker failed	check fuse or circuit breaker and replace or switch on again
		defective mains cord or switch or instrument socket	check instrument cord, switch and socket, replace defective parts
displays remain		faulty mains cord or instrument socket	check instrument cord and socket, replace defective parts
dark	no low voltage supply for	faulty connection from CPU to indication board	check connections on CPU, indication board and connecting leads, replace defective parts
	indication board	faulty indication or CPU board	replace main board completely
	interrupted program	NV-RAM out of socket or not correctly placed	insert the valid NV-RAM and push it correctly into socket
all display elements	CPU program reset may be caused by EMI	reduced voltage supply (<10%)	remedy the failure if the voltage drops often, use a voltage stabiliser
are shortly illuminated		bad or missing ground connection	check all ground connections and the ground connection of all boards
constant	interruption	parameter NV-RAM	no or defective NV-RAM
drive	mechanics	wear out of motor rubber mount	replace motor rubber mounts (at least every three years)
makes noises -no		motor bearings	replace motor completely
good separation result	electrical	defective terminal connection, faulty lead or motor winding	check voltage on motor terminal and winding resistances -see test points on boards
rooun		faulty power electr.	replace main board
	lid coil is not or not sufficiently supplied with voltage	Missing mains voltage	remedy see above, manual opening only at standstill
lid cannot be opened		PTC resistor has released	after a waiting time of 1-2 minutes press key again
		faulty driving circuit	replace main board
by key at standstill	faulty lid coil	faulty coil winding	replace complete locking assy
->"E-17"	lid is not	lid bolt is jamming	push lid centrally into lock and press the key again
	correctly locked	lid is deformed	re-adjust the lid centrally



Service



2.3 Error Codes

Error Indication	Error Cause	Possible Error Source	Corrective Procedure	
" rotor" in speed display	wrong selection of detected rotor	inadmissible speed or rcf value was pre- selected	press start again (within 15s), else wait for rotor standstill, lid OPEN/CLOSE, set value, start	
		rotor not symmetri- cally loaded	open lid, check rotor loading, close lid again and restart	
		base is not sturdy enough and comes into vibrations	change or reinforce the base (table, lorry with lockable wheels, etc.)	
"bAL"	imbalance run	centrifuge drive is not correctly levelled	level the centrifuge correctly, use a spirit level on top of unit	
message appears in		rotor itself has imbalance	rotor must no longer be used, send back to factory	
speed display		drive shaft or rotor fixing is damaged	centrifuge must no longer be used, replace nut and/or motor	
		imbalance NV-RAM	no or defective NV-RAM	
	signal fault	imbalance sensor, sensor board	replace sensor board	
		circuits of main board	replace the main board	
imbalance	o no imbalance	imbalance NV-RAM	wrong NV-RAM data	
but no " bAL "		imbalance sensor	replace sensor board	
message		circuits of main board	replace the main board	
	lid was opened manually during run	forbidden intervention emergency opening device must only be used at standstill	close lid immediately, turn power OFF/ON, press lid down for locking, press start key, press stop to finish run	
"Lid" appears in	protection circuit (15V) interrupted during run	defective micro switch or leads or connectors to micro switch are interrupted	check leads and connectors to micro switch, in case of a faulty micro switch, replace lid lock device completely	
speed display		motor over- temperature switch has tripped (no sufficient air flow or motor has run on 2 phases only)	let motor cool down, then check temperature switch and leads with Ohmmeter	
			check air cooling and circulation	
			check solderless connections XM1-3 and motor windings (see test points in 2.3)	
"OPEn" appears in	15V supply for	loose plug connectors	check plug connectors XA1 and XA2	
speed display by	protection circuit is interrupted at	interrupted leads to micro switches	check leads to micro switches for continuity	
supposedl y closed lid	standstill	defective micro switch	in case of faulty micro switch replace lid lock completely	





Error Codes continued

Error Indication	Error Cause	Possible Error Source	Corrective Procedure
	rotor didn't turn	rotor is jammed	check for easy movement, remove any jamming objects
		motor is jammed	replace motor
"E-00", "E-03"	missing speed signal test: turn rotor by hand, then close the lid	faulty plug or lead connection to speed detection board	check plug contacts and leads, measure speed signal on XW1/3, replace defective parts
message appears in speed display		faulty processing circuit	replace main board
alopiay		connections motor to power electronics	check plug contacts and leads, replace faulty parts
	motor didn't start	motor windings	Replace motor
		driving circuit, FETs	Replace mainboard
"E-02"	program	bad ground connect. EMI troubles	check all ground connections tighten loose screws
message	sequence was disturbed	internal program error	replace the CPU
		-	replace the main board
"E-06"	data lines to key	data lines or soldering connections	check lines and soldering points, replace faulty parts
message	board were	CPU is defective	CPU exchange
ge	disturbed	faulty key or faulty CPU board	replace the main board
E 00"	over-voltage of		check leads and brake resistor, replace defective
" E-08 " message	intermediate circuit	brake resistor driving and/or braking circuits	parts replace the main board
" E-10 " message	NV-RAM is not initialised	Initialising of NV-RAM is not valid	check NV-RAM and socket, insert the correct NV-RAM
"E-11" message	NV-RAM is faulty	no data transfer from NV-RAM to CPU	replace the NV-RAM
		a wrong rotor was installed	wait for standstill, open the lid and install a correct rotor
"E-14"	wrong or faulty rotor detection	mains voltage failure	press stop key, wait for standstill and restart
message	rotor detection	wrong motor phase condition	check rotation direction, if necessary change 2 leads
		faulty detection circuit	replace the main board
" E-15 " message	checksum error	NV-RAM is wrong or defective	replace NV-Ram and insert correctly into socket
" E-16 " message	program interruption	CPU disturbed or defective	replace CPU and /or eliminate disturbance
"E-17"	micro switch does not open after pressing lid	lid is blocked or jammed	press lid centrally in front down again, re-adjust if necessary
lid didn't		defective micro switch or lid lock	replace lid lock device
open		faulty driving circuit	replace the main board
"E-19"	wrong key board	wrong NV-RAM	Replace the correct NV-RAM
message	indication	wrong key board (incl./without cooling)	replace the correct key board





Error Codes continued

Error Indication	Error Cause	Possible Error Source	Corrective Procedure
"E-22"	NV-RAM and	wrong NV-RAM	Replace the correct NV-RAM
" ∟-22 message	CPU didn't match	wrong CPU	Replace the correct CPU
"E-24"	2. NV-RAM is	NV-RAM for curves is	insert the NV-RAM including
message	missing	not (correctly) in place	acceleration./deceleration curves
		no rotor installed	install rotor correctly
"E-25"	pulsing fault of	loose rotor screwing	tighten rotor sturdy
message	message rotor detection	big imbalance on start	rotor, spindle or motor bearing
		faulty pulse detection	distance hall sensor, magnets
"E-26"	Failure of CPU	Checksum error NV	Replace the NV-RAM
message	imbalance	RAM	Replace the main board





2.4 Test Points2.4.1 Test Points 120V model

Test Points	Unit Value	Conditions		
mains terminal XN	120V AC	all given values are related on 120V (±10%) mains voltage for		
board's resistance 337 Ω board's supply				
		in each case measured inter 2 motor leads after reaching selected		
terminal XM		speed - no effective values!		
motor voltage -	65V AC	1000 rpm , swing-out rotor #5197		
values must be the		2000 rpm		
same between all	165V AC	5000 rpm		
3 motor leads	130V AC	5000 rpm, microliter-rotor #5195		
(U , V , W)	210V AC	10000 rpm		
	250V AC	15000 rpm		
		soft iron or digital effective measuring instrument		
motor current I _M	3 * 2,2A	Maximum during acceleration (#5197, 17s)		
cable (1,2,3)	3 * 1,2A	rotor #5197, set speed = 4000 rpm , 200W		
	3 * 0,9A	rotor #5195, set speed = 15000 rpm, 330W		
	3 * 2,5A	maximum during braking phase (#5197, 17s)		
intermediate	320V DC	at standstill		
voltage U _D	355V DC	max. during braking phase (#5195, 30s)		
(inter brake	310V DC	rotor #5197, set speed = 4000 rpm		
resistor's solder	308V DC	rotor #5195, set speed = 15000 rpm		
pin and control resistor R41)	295V DC	shortly at maximum acceleration (#5195, 30s)		
automatic of	5mV DC	1000 rpm, swing-out rotor #5197		
current I _D of	15mV DC	2000 rpm		
intermediate	70mV DC	5000 rpm		
circuit, (measured as voltage drop	15mV DC	5000 rpm, microliter-rotor #5195		
across control	55mV DC	10000 rpm		
resistor R41)	120mV DC	15000 rpm		
$U_{\rm M} = I_{\rm D} * R_{\rm M}$	280mV DC	shortly at maximum acceleration (#5195)		
	–120mV	shortly at maximum braking (#5195)		
motor winding	3x6,4Ω	switch OFF unit, pull off motor plugs,		
resistance 20°C		measure inter 1 -> 2, 2 -> 3, 1 -> 3		
-insulation value	> 10MΩ	resistance inter each phase and motor casing		
brake resistor	0000	switch OFF unit, solder protection O.K.,		
		resistance at 20°C		
plugs XC1/2		condition at reat registering at 20%		
lid solenoid	34Ω	condition at rest, resistance at 20°C		
lid micro switches plug XA1/2 15V DC voltage drop by open lid		voltage drop by open lid		





2.4.2 Test Points 230V model

Test Points	Unit Value	Conditions		
mains terminal XN	230V AC	all given values are related on 230V (±10%) mains voltage for		
board's resistance 1050 Ω		board's supply		
		in each case measured inter 2 motor leads after reaching selected		
terminal XM		speed - no effective values!		
motor voltage -	65V AC	1000 rpm , swing-out rotor #5197		
values must be the		2000 rpm		
same between all	165V AC	5000 rpm		
3 motor leads	130V AC	5000 rpm, microliter-rotor #5195		
(U , V , W)	210V AC	10000 rpm		
	250V AC	15000 rpm		
		soft iron or digital effective measuring instrument		
motor current I _M	3 * 2,2A	Maximum during acceleration (#5197, 17s)		
cable (1,2,3)	3 * 1,2A	rotor #5197, set speed = 4000 rpm , 200W		
	3 * 0,9A	rotor #5195, set speed = 15000 rpm, 330W		
	3 * 2,5A	maximum during braking phase (#5197, 17s)		
intermediate 320V D		at standstill		
voltage U _D	355V DC	max. during braking phase (#5195, 30s)		
(inter brake	310V DC	rotor #5197, set speed = 4000 rpm		
resistor's solder	308V DC	rotor #5195, set speed = 15000 rpm		
pin and control resistor R41)	295V DC	shortly at maximum acceleration (#5195, 30s)		
ourrent L of	5mV DC	1000 rpm, swing-out rotor #5197		
current I _D of	15mV DC	2000 rpm		
intermediate	70mV DC	5000 rpm		
circuit, (measured	15mV DC	5000 rpm, microliter-rotor #5195		
as voltage drop across control	55mV DC	10000 rpm		
resistor R41)	120mV DC	15000 rpm		
$U_{\rm M} = I_{\rm D} * R_{\rm M}$	280mV DC	shortly at maximum acceleration (#5195)		
	–120mV	shortly at maximum braking (#5195)		
motor winding	3x6,4Ω	switch OFF unit, pull off motor plugs,		
resistance 20°C	,	measure inter 1 -> 2, 2 -> 3, 1 -> 3		
-insulation value $> 10M\Omega$		resistance inter each phase and motor casing		
brake resistor	0000	switch OFF unit, solder protection O.K.,		
		resistance at 20°C		
plugs XC1/2 condition at rest, resistance at 20°C		condition at rest, resistance at 20°C		
lid solenoid lid micro switches	15V DC	voltage drop by open lid		
plug XA1/2				





2.5 Imbalance Behaviour

• Install in table available rotor(s) in unloaded condition

Rotor	Run through weight	Cut off weight
Swing-out 4x100mL #5197	10g	20g
Angle 24x2mL Alu #5195	5g	10g

- Insert rotor dependent **cut-off weights** into opposite buckets. Check this at all 4 possibilities by putting the weights pair by pair into the other buckets. The centrifuge must stop 4 times indicating "bAL" message in case of false behaviour see trouble shooting: no "bAL" indication.
- Insert the **admissible imbalance weights** in the same manner, the centrifuge must run through 4 times to maximum rotor speed.

2.6 Cleaning of Instrument Parts

ATTENTION - WARNING!

The electrical and electronic components must not be cleaned with moist detergents!

For Cleaning the centrifuge housing or its accessories see Operating Instructions section 1 (maintenance and care)

Electronic components
Clean dusty components ca

Clean dusty components carefully with a dry and soft brush and remove loose dust with a vacuum cleaner.

• Vent holes Remove dirt from the vent grid behind the front panel by using a brush and vacuum cleaner.